

## Nearest Neighbors Algorithm

- Store all the training data as feature vectors
- Prediction for new, test data point: return the label of the closest training point

(you are the company you keep...)

What is the predicted color for a new point (-2, -2)? Or for (2, 2)?



# k Nearest Neighbors Algorithm

- Choose some integer value of k (say, 3)
- Compute the *k* closest training points to the test data point
- Return the majority label

What is the predicted color for a new point (-1.1, 1.7)?







# Choosing k

- *k* is a free "hyperparameter" of the algorithm. How do we choose it?
- One option: try different values of k when evaluating on test data
- Rather than split data into two parts, training and test, we split data into three parts, training and validation and test.
  - Use the validation data as "pseudo-test data" to **tune** (choose best) *k*
  - Do final evaluation on the test data only once

























# kNN Complexity

- Given *n* training examples and *d* features
- Training step
  - Time: approximately zero; just store the data points
  - Space: size of training data (n x d)
- Testing step (for each test example)

   Time?











• Compute the mean (i.e., average) for each of the features in the training data and subtract this mean from each feature value

For each of the  $1 \le i \le n$  training examples and  $1 \le i \le d$  features, we subtract the mean:  $x_{i,j} = x_{i,j} - \mu_i$ 

where the mean of the *j*<sup>th</sup> feature is  $\mu_j = \frac{1}{n} \sum_{1 \le i \le n} x_{i,j}$ 

Data will then be centered around zero ٠





• Compute the standard deviation for each of the features in the training data and divide each feature value by this standard deviation



For each of the  $1 \le i \le n$  training examples and  $1 \le j \le d$  features, we divide by the standard deviation:  $x_{i,i} = x_{i,i} / \sigma_i$ 

where the standard deviation of the *j*<sup>th</sup> feature is  $\sigma_j = \sqrt{\frac{1}{n} \sum_{1 \le i \le n} (x_{i,j} - \mu_j)^2}$ 

Data will then have comparable scale

# Feature Scaling • Compute the standard deviation for each of the features in the training data and divide each feature value by this standard deviation For each of the 1 $\leq i \leq n$ training examples and 1 $\leq j \leq d$ features, we divide by the standard deviation: $x_{i,j} = x_{i,j} \neq \sigma_j$ where the standard deviation of the j<sup>th</sup> feature is $\sigma_j = \sqrt{\frac{1}{n} \sum_{1 \leq i \leq n} (x_{i,j} - \mu_j)^2}$ • Data will then have comparable scale

## Feature Scaling - Test Data

- When scaling the training data, we **store** the mean and standard deviation values that we compute for each feature as part of the scaling process
- When given a testing example, we need to make sure that it is on a comparable scale as the training data. Thus, we scale it using the stored mean and standard deviation values.

For the *i*<sup>th</sup> testing example, we scale each of its  $1 \le j \le d$  features by subtracting the *j*<sup>th</sup> mean ( $\mu_i$ ) and dividing by the *j*<sup>th</sup> standard deviation ( $\sigma_i$ ):

$$x_{i,j} = (x_{i,j} - \mu_j) / \sigma_j$$

## Pros and Cons of kNN

### Pros

- Simple and intuitive
- Can be used with multiple classes (not just 2)
- Data do not have to be linearly separable

### Cons

- Need to store large full training data
- Test time is SLOOOWW
  - Prefer to pay for expensive training in exchange for fast prediction

# Looking ahead

- *k*NN is an instance-based classifier: must carry around training data (waste of space)
- Training easy
- Testing hard

#### Future methods will be

- Parametric classifiers: compute a small "model" and then throw away training data
- Training hard
- Testing easy

# Looking ahead: linear classifiers

- Training: find a dividing "hyperplane" between two classes
- Testing: check which side of hyperplane the new point falls in



