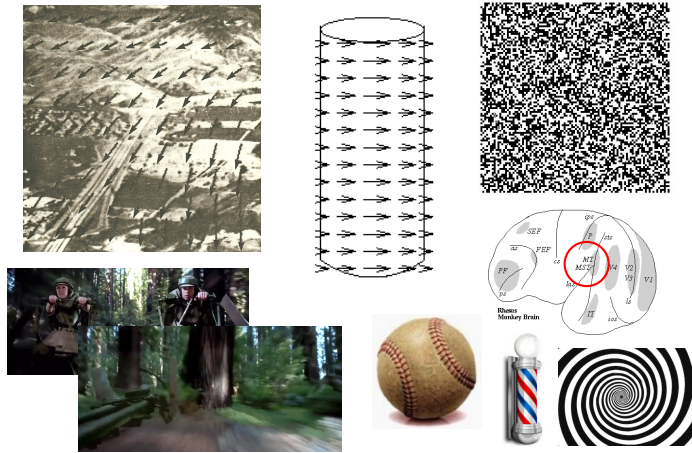
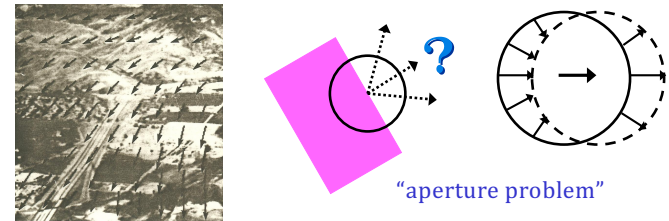


## Analysis of visual motion



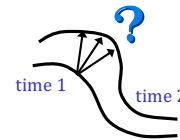
1

## Measuring image motion



velocity field

"local" motion detectors only measure *component of motion perpendicular to moving edge*

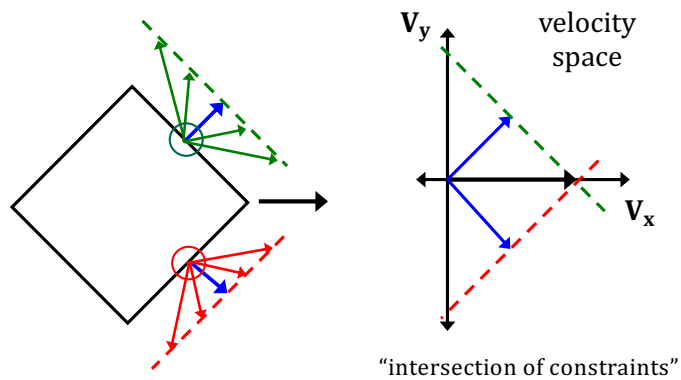


2D velocity field not determined *uniquely* from the changing image

need *additional constraint* to compute a unique velocity field

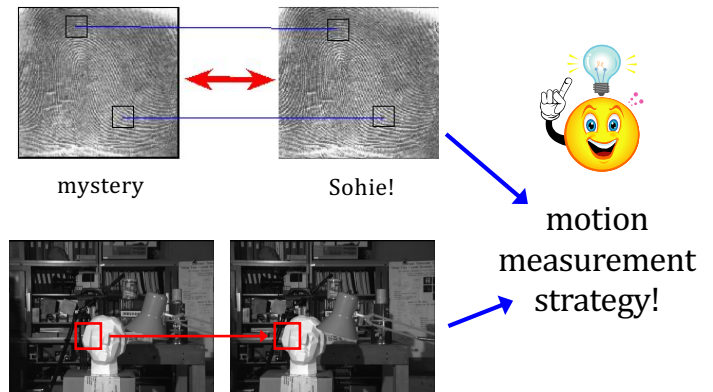
2

## Option 1: Assume *pure translation*



"intersection of constraints"

3



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### Practical considerations for methods based on pure translation:

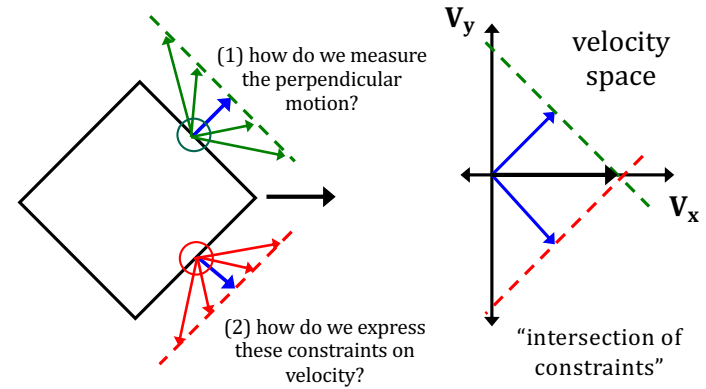
- Error in initial motion measurements
- Local image features may have small range of orientations
- Velocities not constant locally

But... such strategies are good for

- detecting sudden movements
- tracking
- detecting boundaries

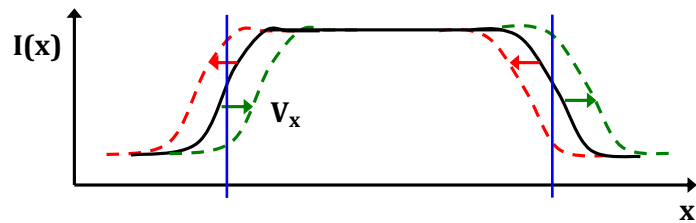
5

### Goals for the rest of this video



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### Measuring motion in one dimension



$V_x$  = velocity in x direction

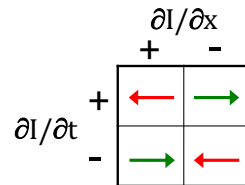
• rightward movement:  $V_x > 0$

• leftward movement:  $V_x < 0$

• speed:  $|V_x|$

• pixels/time step

$$V_x = - \frac{\partial I / \partial t}{\partial I / \partial x}$$



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### Measuring motion components in 2-D

(1) gradient of image intensity

$$\nabla I = (\partial I / \partial x, \partial I / \partial y)$$

(2) time derivative

$$\partial I / \partial t$$

(3) velocity along gradient:

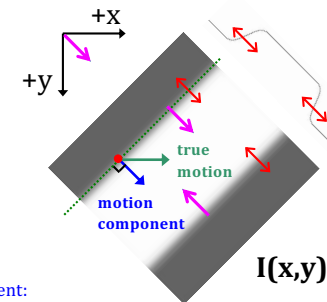
$$v^\perp$$

• movement in direction of gradient:

$$v^\perp > 0$$

• movement opposite direction of gradient:

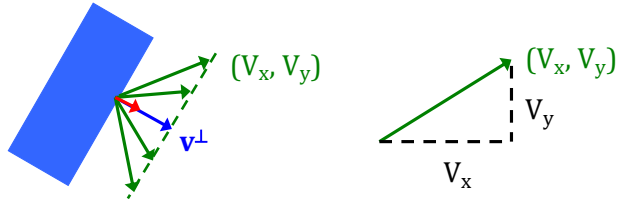
$$v^\perp < 0$$



$$v^\perp = - \frac{\partial I / \partial t}{|\nabla I|} = - \frac{\partial I / \partial t}{[(\partial I / \partial x)^2 + (\partial I / \partial y)^2]^{1/2}}$$

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## 2D velocities $(V_x, V_y)$ consistent with $v^\perp$



All  $(V_x, V_y)$  such that the component of  $(V_x, V_y)$  in the direction of the gradient is  $v^\perp$

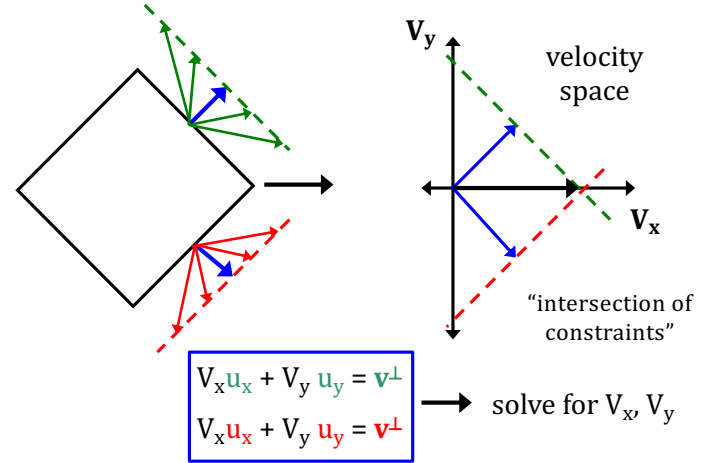
$(u_x, u_y)$ : unit vector in direction of gradient

Use the dot product:  $(V_x, V_y) \cdot (u_x, u_y) = v^\perp$

$$V_x u_x + V_y u_y = v^\perp$$

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## Computing velocity from motion components



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