

# Compound Data and Memory Management

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## Compound Data

Simple data are atomic — they have no parts. E.g. integers, floats booleans, characters. (But some languages, esp. C, can view even simple data as sequences of bits.) Compound data have parts:

- Products: datum has multiple value components. E.g. pairs, tuples, arrays, vectors, strings, records, structs, etc.
- Sums: datum is a tagged choice of several values. E.g., oneofs, variants, tagged sums, tagged unions, discriminated unions.
- Sum of Products: datum is one of several possible tagged products: E.g. linked lists, binary trees, abstract syntax trees, s-expressions. Implemented via OCaml data types, Java objects, Pascal variant records, XML trees.

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# Product Dimensions

- How are product values created and later decomposed into parts? Is there special syntax for creating the product or selecting/changing its parts?
- Are the components of the product indexed by position or by name? If by position, is indexing 0 or 1 based?
- When accessing a component, can its index be calculated or must an index be a manifest constant?
- Are the components values (as in call-by-value) or computations (as in call-by-name/call-by-need)?
- Are the components of the product immutable or mutable?
- Is the length of the product fixed or variable?
- Are all components of the product required to have the “same type,” i.e., are products *homogeneous*?
- When products are nested, are the nested components all required to have the same size and/or “shape”?
- How are products passed as arguments, returned as results, and stored in assignments?
- Can the lifetime of a product exceed the lifetime of an invocation of a procedure in which it is created?

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## Pairs: The Simplest Product

- OCaml's immutable pairs has parts accessible via `fst` and `snd` or pattern matching:

```
# let p = (17,true);;
val p : int * bool = (17, true)
# if snd(p) then fst(p)*2 else 42;;
- : int = 34
# let (i,b) = p in if b then i*2 else 42;;
- : int = 34
```
- Standard ML of New Jersey (SMLNJ) has immutable pairs whose parts are accessible via `#1` and `#2` or pattern matching:

```
- val p = (17,true);
val p = (17,true) : int * bool
- if #2(p) then #1(p)*2 else 42;
val it = 34 : int
- let val (i,b) = p in if b then i*2 else 42 end;
val it = 34 : int
```
- Pair components can be made mutable via explicit cells. E.g.

```
# let p = (ref 17, true) in (fst p := (! (fst p) + 1); p);;
- : int ref * bool = ({contents = 18}, true)
```

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## Pairs in Scheme

- Dynamically typed mutable pairs in Scheme created via `cons`, selected via `car` and `cdr`, and changed via `set-car!` and `set-cdr!`.

```
(let* ((p (cons 17 #t))
      (a (car p)))
  (begin (set-car! p (cdr p)) (set-cdr! p a) p))
;Value 1: (#t . 17) ; A "dotted pair"
```

- Scheme lists are just `cdr`-linked pairs terminated with the empty list `'()` (equivalent to `#f` in some implementations).

```
(cons 17 (cons #t (cons "foo" '())))
;Value 2: (17 #t "foo") ; Abbreviation of (17 . (#t . ("foo" . ())))

(list 17 #t "foo")
;Value 3: (17 #t "foo")
```

- The quotation notation for symbols (`(quote symbol)`), abbreviated `'symbol` is also used for dotted pairs and lists.

```
'((17 . #t) (fun (a b) (bind c (+ a b) (/ a b))))
;Value 4: ((17 . #t) (fun (a b) (bind c (+ a b) (/ a b))))
```

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## Pairs in Other Languages

- Can make immutable and mutable pairs in Java, but have type headaches:
  - *Approach 1*: make different class for every pair of component types. Yuck!
  - *Approach 2*: make one `Pair` class that holds two `Objects`, but then have to (1) wrap/unwrap small values like integers and characters and (2) cast components upon extraction. Yuck!
  - *Approach 3*: Java 1.5 supports *generic classes* that are parameterized by type. Can define a class `Pair<S, T>` that pairs objects of type `S` with those of type `T` and can instantiate these with any object types. Wrapping and casting is still necessary, but is handled automatically by Java in most cases.
- Can use C structs (records), but
  - need different struct type for every pair of component types;
  - we'll see that semantics is somewhat surprising.

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## Product Components can be Lazy

Parameter passing mechanisms can be applied to product components: they can be values (call-by-value), thunks (call-by-name), or memoized promised (call-by-lazy). E.g. what is the behavior of the following example under CBV, CBN, and CBL?

```
(bind p (pair (println (+ 1 2))
              (println (+ 3 4))))
(+ (snd p) (* (fst p) (fst p)))
```

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## Parameter Passing of Mutable Products

Consider passing mutable pairs in HOILIC-like language:

```
(bind p (pair 2 3)
      (bind f (fun (r) (seq (setfst r (+ (fst r) (snd r)))
                          (setsnd p (* (fst p) (snd p)))))
            (seq (f p) (println (fst p)) (println (snd p)))))
```

- In **call-by-value-sharing** (Ocaml, Scheme, Java, C arrays), parameter  $r$  shares the same mutable storage with  $p$ .
- In **call-by-value-copy** (C structs, Pascal arrays and records), parameter  $r$  has mutable slots distinct from  $p$  that are initialized to the contents of  $p$ 's slots.

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# Positional Products

- Both OCaml and SMLNJ support arbitrary length statically typed immutable heterogeneous tuples and fixed-length mutable homogeneous arrays. In OCaml, a general tuple is only decomposable via pattern matching; in SMLNJ, the `#i` syntax may also be used.
- Scheme has dynamically typed arbitrary-length mutable heterogeneous lists and fixed-length mutable heterogeneous vectors.
- Java has statically typed mutable fixed-length homogeneous arrays and extensible heterogeneous (sort of, via `Object` subtyping) vectors.
- C has (weakly) statically typed mutable fixed-length homogeneous arrays, but since arrays don't "know" size, can access out-of-bounds array indices.
- Pascal has statically typed mutable fixed-length homogeneous arrays. Bizarrely, array size is part of type, so procedures aren't polymorphic over arrays of different size!

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# Products with Named Components

Many languages support products with named components. E.g.

- OCaml/SMLNJ records have immutable components by default. (SMLNJ tuples are just sugar for records.)
- Java class instances have mutable components.
- C structs have mutable components.
- Pascal records have mutable components.
- Common Lisps `defstruct` facility manipulates records with mutable components.

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# Records in OCaml

```
# type person = name: string; mutable age: int; sex: bool;;
type person = name : string; mutable age : int; sex : bool;

# let wendy = name="Wendy Wellesley"; age=19; sex=true;;
val wendy : person = name = "Wendy Wellesley"; age = 19; sex = true

# let will = name="William Wellesley"; age=57; sex=false;;
val will : person = name = "William Wellesley"; age = 57; sex = false

# let wanda = wendy with name = "Wanda Wellesley"; (* new person record
val wanda : person = name = "Wanda Wellesley"; age = 19; sex = true

# wendy.age;;
- : int = 19

# wendy.age <- wendy.age + 1;;
- : unit = ()

# wendy.age;;
- : int = 20

# wanda.age;;
- : int = 19
Note: the names name, age, and sex are in a single global namespace for record field
names. A declaration of a new record type with one of these names makes the name
inaccessible in the old record type.
```

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# Stack vs. Heap

Programs typically manipulate two areas of memory:

**Stack:** (i.e., Java Execution Land in CS11/CS230) The stack typically holds *activation/execution frames* for function/procedure/method invocations. Variables and compound data whose lifetime does not outlast the invocation may be stored in the frame. C/Java execution frames and local C compound data (arrays/structs) are stored here. When the invocation returns, the frame is popped off the stack, implicitly deallocating any data in the frame.

**Heap:** (i.e., Java Object Land in CS11/CS230) The heap holds *data blocks* whose lifetime may outlast the function/procedure/method invocation in which it was created. Java objects and Ocaml/Haskell/Scheme data/closures/environments are stored here. Heap blocks can be deallocated manually (as in C/Ada/Pascal) or automatically (via garbage collection, as in Java/Ocaml/Haskell/Scheme).

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## Inspecting the C Stack with Invalid Array References

```
int test (int* a, int lo, int hi) {
    int i; for (i=lo; i<=hi; i++)
        printf("%x:a[%d]=%d (%x)\n", &a[i], i, a[i], a[i]); }

int main () { int b[] = {17,42}; test(b, -17, 1); }

linux> gcc -o arrayrefs arrayrefs.c; ./arrayrefs
bffff74c:a[-17]=1073823076 (40013d64)    # return addr. of printf (stale)
bffff750:a[-16]=134513912 (80484f8)    # address of format string
bffff754:a[-15]=-1073744048 (bffff750) # address of &a[i] (stale)
bffff758:a[-14]=-15 (ffffff1)         # i (stale)
bffff75c:a[-13]=-15 (ffffff1)         # a[i] (stale)
bffff760:a[-12]=-15 (ffffff1)         # a[i] (stale)
...                                     # unused slots
bffff774:a[-7]=-7 (ffffff9)           # i (for i = -7)
bffff778:a[-6]=-1073743976 (bffff798) # saved base pointer for main
bffff77c:a[-5]=134513799 (8048487)    # return address of test call
bffff780:a[-4]=-1073743984 (bffff790) # 1st arg to test = &b[0]
bffff784:a[-3]=-17 (ffffffef)        # 2nd arg to test
bffff788:a[-2]=1 (1)                 # 3rd arg to test
bffff78c:a[-1]=134513633 (80483e1)    # unused slot
bffff790:a[0]=17 (11)                 # b[0]
bffff794:a[1]=42 (2a)                 # b[1]
```

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## String Overwriting in C

```
// strings.c
// illustrates how one string can overwrite another in c
int main () {
    char a[] = "foo";
    char b[] = "bar";
    printf("a=%s; b=%s\n",a,b);
    strcpy(b,"bazquux");
    // strcpy(dest,src) is a built-in string copy function
    printf("a=%s; b=%s\n",a,b);
}
```

```
linux> gcc -o strings strings.c; ./strings
a=foo; b=bar
a=uux; b=bazquux
```

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## Stack-Allocated C Arrays Cannot be Returned

```
// stack-arrays.c
void printarray(char* s, int* a, int n) {
    int i; for (i = 0; i < n; i++) {printf("%s[%d] = %d\t", s, i, a[i]);}
    printf("\n");}

int* elts (int n, int scale) {
    int a[n]; // Stack allocated array
    int i; for (i = 0; i < n; i++) { a[i] = scale*i; }
    printarray("a",a,n); return a; }

int main () ] {
    int* b; int* c; b = elts(4,1); printarray("b",b,4);
    c = elts(4,2); printarray("b",b,4); printarray("c",c,4); }
```

```
linux> gcc -o stack-arrays stack-arrays.c; ./stack-arrays
```

```
stack-arrays.c: In function 'elts':
```

```
stack-arrays.c:20: warning: function returns address of local variable
```

```
a[0] = 0  a[1] = 1  a[2] = 2  a[3] = 3
```

```
b[0] = 0  b[1] = 1108542220  b[2] = -1073744264  b[3] = 134513720
```

```
a[0] = 0  a[1] = 2  a[2] = 4  a[3] = 6
```

```
b[0] = 0  b[1] = 1108542220  b[2] = -1073744264  b[3] = 134513720
```

```
c[0] = 0  a[1] = 1108542220  c[2] = -1073744264  c[3] = 134513720
```

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## One Way to Fix Problem

```
// stack-arrays2.c
void printarray(char* s, int* a, int n) {
    int i; for (i = 0; i < n; i++) {printf("%s[%d] = %d\t", s, i, a[i]);}
    printf("\n");}

int* elts (int* a, int n, int scale) {
    // Pass in already allocated array a to elts
    int i; for (i = 0; i < n; i++) { a[i] = scale*i; }
    printarray("a",a,n); return a; }

int main () {
    // Fix problem in stack-arrays.c by allocating arrays outside elts;
    int b[4]; int c[4]; elts(b,4,1); printarray("b",b,4);
    elts(c,4,2); printarray("b",b,4); printarray("c",c,4); }
```

```
linux> gcc -o stack-arrays2 stack-arrays2.c; ./stack-arrays2
```

```
a[0] = 0      a[1] = 1      a[2] = 2      a[3] = 3
```

```
b[0] = 0      b[1] = 1      b[2] = 2      b[3] = 3
```

```
a[0] = 0      a[1] = 2      a[2] = 4      a[3] = 6
```

```
b[0] = 0      b[1] = 1      b[2] = 2      b[3] = 3
```

```
c[0] = 0      c[1] = 2      c[2] = 4      c[3] = 6
```

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## Another Way to Fix Problem: Heap Allocation

C provides the following functions for manual heap storage management:

```
void *malloc (size_t size);
```

allocates `size` bytes and returns a pointer to the allocated memory. The memory is not cleared. Returns the `NULL` pointer if the request fails.

```
void free(void *ptr);
```

frees the memory space pointed to by `ptr`, which must have been returned by a previous call to `malloc()`. Otherwise, or if `free(ptr)` has already been called before, undefined behaviour occurs. If `ptr` is `NULL`, no operation is performed.

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## Heap Allocated Arrays in C

```
// heap-arrays.c
void printarray(char* s, int* a, int n) {
    int i; for (i = 0; i < n; i++) {printf("%s[%d] = %d\t", s, i, a[i]);}
    printf("\n");}

int* elts (int n, int scale) {
    int* a = (int *) malloc(n*sizeof(int)); // Heap allocated array:
    int i; for (i = 0; i < n; i++) { a[i] = scale*i;}
    printarray("a",a,n); return a;}

int main () {
    int* b; int* c; b = elts(4,1); printarray("b",b,4);
    c = elts(4,2); printarray("b",b,4); printarray("c",c,4);}

linux> gcc -o heap-arrays heap-arrays.c; ./heap-arrays
a[0] = 0      a[1] = 1      a[2] = 2      a[3] = 3
b[0] = 0      b[1] = 1      b[2] = 2      b[3] = 3
a[0] = 0      a[1] = 2      a[2] = 4      a[3] = 6
b[0] = 0      b[1] = 1      b[2] = 2      b[3] = 3
c[0] = 0      c[1] = 2      c[2] = 4      c[3] = 6
```

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## Problems with Manual Heap Storage Management

- **Storage Leak:** If do not `free` storage that is no longer accessible, can run out of heap space.
- **Dangling Pointer:** If `free` a pointer to a heap block that is still in use, unpredictable behavior can result.

```
// dangling.c
int main () {
    int* a; int *b;
    a = (int *) malloc(10);
    a[0] = 17;
    free(a); // Any reference to a after this is dangling
    b = (int *) malloc(10);
    b[0] = 42;
    printf("a[0]=%d; b[0]=%d\n", a[0], b[0]);}

```

```
linux> gcc -o dangling dangling.c; ./dangling
a[0]=42; b[0]=42

```

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## Automatic Heap Storage Management: Garbage Collection

- Can automatically reclaim storage that is no longer accessible from a program via a process called **garbage collection (GC)**.
- All storage blocks reachable from the **root set** (typically processor registers) are **live** and are preserved. All others are **dead** and are reclaimed.
- We'll consider several approaches to GC in the context of the following Scheme example:

```
(let* ((a (cons 1 (cons 2 '())))
      (b (cons 3 (cons 4 '())))
      (c (cons a b)))
  (begin (set-cdr! (cdr b) b)
         (set-cdr! (cdr a) (cdr a))
         (set-car! c (cdr b))
         c))

```

Assume the returned pair is the GC root.

- Some languages allow specifying actions to perform when a storage block is reclaimed. E.g., Java `finalize` method and C++ destructors.
- Garbage collection is essential to program modularity. Without it, how can we know in a large system when it's safe to free memory?

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# GC: Reference Counting

- *Idea:* Keep track of the number of pointers to each heap-allocated block and reclaim the block when this number reaches 0;
- Some C++ implementations use reference counting for GC.
- *Advantage:* Easy to perform incrementally.
- *Disadvantages:*
  - Need space to maintain the reference counts.
  - Reference counts must be updated at every allocation and assignment;
  - Doesn't reclaim cyclic data.

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# GC: Mark-Sweep

- *Idea:* Maintain a free list of all storage blocks from which new storage is allocated. For simplicity, assume all blocks are pairs. Each block has a **mark bit** that is initially false. When free list is exhausted, perform GC in two phases:
  1. **Mark phase** Trace through all blocks accessible from root set, setting the mark bit of every accessible block.
  2. **Sweep phase** Sweep through all blocks. Unmarked blocks are reclaimed by adding them to the free list. Marked blocks have their mark bit unset.
- *Advantages:* (1) Easy to understand and (2) only requires one bit per block.
- *Disadvantages:*
  - Storage for mark bits.
  - Cleverness needed to avoid recursion stack in mark phase.
  - System must pause while GC takes place.
  - Sweep phase touches all memory (mark phase touches only live memory).
  - Memory fragmentation.

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# GC: Stop and Copy

- *Idea:* Split memory into two equal-sized **semispaces**. Allocate blocks from “current” semispace (other used only for collection). When current semispace is exhausted, copy only accessible blocks to other semispace, and make it the new “current” semispace.
- *Advantages:*
  - Simple to allocate and trace arbitrary sized blocks.
  - Copy phase touches only live memory.
  - Copy phase compacts memory, avoiding fragmentation.
- *Disadvantages:*
  - Half of memory is unused!
  - Need to pause for GC (but there are incremental versions).

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# GC: Stop and Copy Algorithm

Call exhausted semispace **from-space** and the other semispace **to-space**. GC copies live blocks in from-space to to-space using two pointers into to-space named `scan` and `free`.  
Invariants: (1)  $scan \leq free$ ; (2) pointers before `scan` point to to-space; (3) pointers between `scan` and `free` point to from-space; (4) from-space blocks already moved to to-space contain a forwarding address to to-space in first slot.

```
// Pseudocode
copy k root pointers beginning of to-space
scan = beginning of to-space
free = scan + k
while scan != free
    if mem[scan] is pointer to not-yet-moved from-space block then
        copy block to mem[free .. free+(n-1)]; // assume n is block size
        mem[mem[scan]] = free; // Leave forwarding address
        mem[scan] = free; // Update pointer to to-space.
        free = free + n;
    else if mem[scan] is pointer to already moved from-space block then
        mem[scan] = mem[mem[scan]]; // Use forwarding address
    // Do nothing if mem[scan] is a non-pointer
    scan = scan + 1
// When scan = free, collection is done. Start allocating from free.
```

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# GC: Conservative GC

- Precise GC requires distinguishing pointers and non-pointers.
- In some language implementations (esp. C, C++) this is not possible.
- **Conservative GC** treats everything that *might be* a pointer as a pointer. Will preserve some blocks that are reclaimed in precise systems.

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# C Points as Structs

```
// points-struct.c
typedef struct P {int x; int y;} point;
point scaledCopy (int s, point p) {
    point q; q.x = s * p.x; q.y = s * p.y; return q;}
void scale1 (int s, point p) { // Call by copy, not sharing!
    p.x = s * p.x; p.y = s * p.y; }
void scale2 (int s, point* p) {
    (*p).x = s * (*p).x; (*p).y = s * (*p).y; }
void printPoint (point p) {
    printf("x=%d;y=%d\n", p.x, p.y); }
int main () {
    point a,b; a.x = 1; a.y = 2;
    b = scaledCopy(3,a); printPoint(a); printPoint(b);
    scale1(4,a); scale2(5,&b); printPoint(a); printPoint(b);}
linux> gcc -o points-struct points-struct.c; ./points-struct
x=1;y=2
x=3;y=6
x=1;y=2
x=15;y=30
```

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## C Points as Stack-Allocated Arrays

```
// points-array.c
/* Represent a point as a 2-slot integer stack array,
   with x in slot 0 and y in slot 1. */
typedef int point[2];
void scaledCopy (int s, point p, point q) { // Must pass in result array
    q[0] = s * p[0]; q[1] = s * p[1]; }
void scale1 (int s, point p) { // Call by sharing!
    p[0] = s * p[0]; p[1] = s * p[1]; }
void scale2 (int s, point* p) {
    (*p)[0] = s * (*p)[0]; (*p)[1] = s * (*p)[1]; }
void printPoint (point p) {printf("x=%d;y=%d\n", p[0], p[1]); }
int main () { point a,b; a[0] = 1; a[1] = 2;
    scaledCopy(3,a,b); printPoint(a); printPoint(b);
    scale1(4,a); scale2(5,&b); printPoint(a); printPoint(b); }

linux> gcc -o points-array points-sarray.c; ./points-sarray
x=1;y=2
x=3;y=6
x=4;y=8
x=15;y=30
```

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## C Points as Heap-Allocated Arrays

```
// points-harray.c
/* Represent a point as a 2-slot integer heap array,
   with x in slot 0 and y in slot 1. */
typedef int* point;
point makePoint (int x, int y) {
    point p = (point) malloc(2*sizeof(int));
    p[0] = x; p[1] = y; return p;}
point scaledCopy (int s, point p) { return makePoint(s*p[0], s*p[1]);}
void scale (int s, point p) { p[0] = s*p[0]; p[1] = s*p[1]; }
void printPoint (point p) { printf("x=%d;y=%d\n", p[0], p[1]); }
int main () { point a,b; a = makePoint(1,2);
    b = scaledCopy(3,a); printPoint(a); printPoint(b);
    scale(4,a); scale(5,b); printPoint(a); printPoint(b); }

linux> gcc -o points-harray points-harray.c; ./points-harray
x=1;y=2
x=3;y=6
x=4;y=8
x=15;y=30
```

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# Integer Lists in C

```
// sumlist.c
#include <stddef.h>
typedef struct IL {int head; struct IL *tail;} intlist;
int sumlist (intlist* lst) {
    if (lst == NULL) return 0;
    else return (*lst).head + sumlist((*lst).tail);}
intlist* fromTo (int lo, int hi) {
    intlist* result;
    if (lo > hi) return NULL;
    else { result = (intlist*) malloc(sizeof(intlist));
          (*result).head = lo;
          (*result).tail = fromTo(lo + 1, hi);
          return result; } }
int main () {
    printf("sumlist(fromTo(1,10))=%d\n", sumlist(fromTo(1,10))); }
linux> gcc -o sumlist sumlist.c; ./sumlist
sumlist(fromTo(1,10))=55
```