# Analysis of Motion 

## Measuring motion in biological vision systems



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## Two-stage motion measurement

motion components $\rightarrow$ 2D image motion
Movshon, Adelson, Gizzi \& Newsome


V1: high \% of cells selective for direction of motion (especially in layer that projects to MT) MT: high \% of cells selective for direction and speed of motion lesions in MT $\rightarrow$ behavioral deficits in motion tasks

## Testing with sine-wave "plaids" <br>  <br> Moving plaid demo: www.georgemather.com <br> Movshon et al. recorded responses of neurons in area MT to moving plaids with different component gratings

## Logic behind the experiments...


(1)

(2)

(3)

Component cells measure perpendicular components of motion e.g. selective for vertical features moving right predicted responses: (1)
(3)

Pattern cells integrate motion components
e.g. selective for rightward motion of pattern
predicted responses: (1)
(2)
(3)

## Movshon et al. observations:

- Cortical area V1:
all neurons behaved like component cells
- Cortical area MT:
layers 4 \& 6: component cells

Evidence for two-stage motion measurement!
layers $2,3,5$ : pattern cells

- Perceptually, two components are not integrated if:
large difference in spatial frequency
large difference in speed
components have different stereo disparity


## Integrating motion over the image

- integration along contours vs. over 2D areas:



## Option 2: Smoothness assumption:

Compute a velocity field that:
(1) is consistent with local measurements of image motion (perpendicular components)
(2) has the least amount of variation possible

Pure Translation:


## When is the smoothest velocity field correct?

Rotation of rigid objects in 2D and 3D:

true \& smoothest velocity field

true \& smoothest velocity field

initial motion measurements

When is it wrong?

kinetic depth effect Wallach \& O'Connell

motion illusions

## Computing the smoothest velocity field



Find $\left(V_{x_{\mathrm{i}}}, V_{y_{\mathrm{i}}}\right)$ that minimize:

$$
\begin{aligned}
& \Sigma\left(\mathrm{V}_{\mathrm{x}_{\mathrm{i}} \mathrm{u}_{\mathrm{x}_{\mathrm{i}}}}+\mathrm{V}_{\left.\mathrm{y}_{\mathrm{i}} \mathrm{u}_{\mathrm{y}_{\mathrm{i}}}-\mathrm{V}_{\mathrm{i}}^{\perp}\right)^{2}+\lambda\left[\left(\mathrm{V}_{\mathrm{x}_{\mathrm{i}+1}}-\mathrm{V}_{\mathrm{x}_{\mathrm{i}}}\right)^{2}+\left(\mathrm{V}_{\mathrm{y}_{\mathrm{i}+1}}-\mathrm{V}_{\mathrm{y}_{\mathrm{i}}}\right)^{2}\right]}^{\text {deviation from image }}+\quad\right. \text { variation in velocity } \\
& \text { motion measurements }
\end{aligned}
$$

