### Processes

Focus:

Process model

Process management case study: Unix/Linux/Mac OS X (Windows is a little different.)

## **Operating Systems**

**Problem: unwieldy hardware resources** 

**Solution: operating system** 

## **Operating Systems**, a 240 view

### Focus: key abstractions provided by kernel

barely scraping the surface

### **Abstractions:**

process

virtual memory

### Virtualization mechanisms and hardware support:

context-switching

exceptional control flow

address translation, paging, TLBs

## Processes

### Program = code (static)

### **Process** = a running program instance (dynamic)

code + state

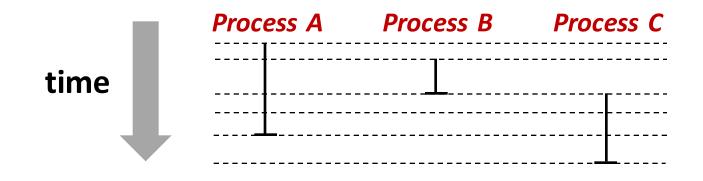
**Key illusions:** 

Why are these abstractions important?

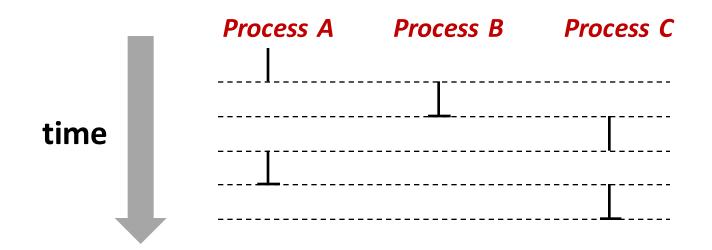
How are these abstractions implemented?

# Implementing logical control flow

Abstraction: every process has full control over the CPU



Implementation: time-sharing

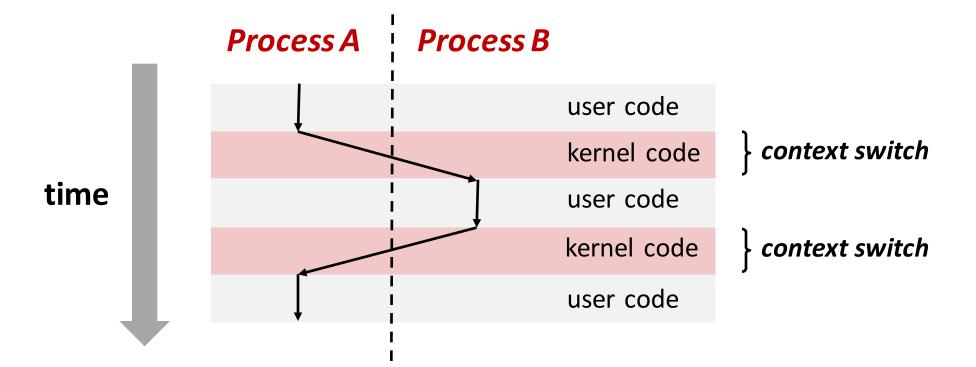


# **Context Switching**

*Kernel* (shared OS code) switches between processes

### Control flow passes between processes via context switch.





# fork

### pid\_t fork()

- **1.** Clone current *parent* process to create identical *child* process, including all state (memory, registers, program counter, ...).
- 2. Continue executing both copies with *one difference:* 
  - returns 0 to the child process
  - returns child's process ID (pid) to the parent process

```
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

fork is unique: called *in one process,* returns *in two processes!* 

(once in parent, once in child)

## Creating a new process with **fork**

#### Process n

```
pid_t pid = fork();
if (pid == 0) {
    printf("hello from child\n");
} else {
    printf("hello from parent\n");
}
```

#### Child Process m

hello from parent

Which prints first?

hello from child

# fork again

#### Parent and child continue from private copies of same state.

Memory contents (code, globals, heap, stack, etc.), Register contents, program counter, file descriptors...

#### **Only difference: return value** from fork()

Relative execution order of parent/child after fork() undefined

```
void fork1() {
    int x = 1;
    pid_t pid = fork();
    if (pid == 0) {
        printf("Child has x = %d\n", ++x);
    } else {
        printf("Parent has x = %d\n", --x);
    }
    printf("Bye from process %d with x = %d\n", getpid(), x);
}
```

## fork-exec

#### fork-exec model:

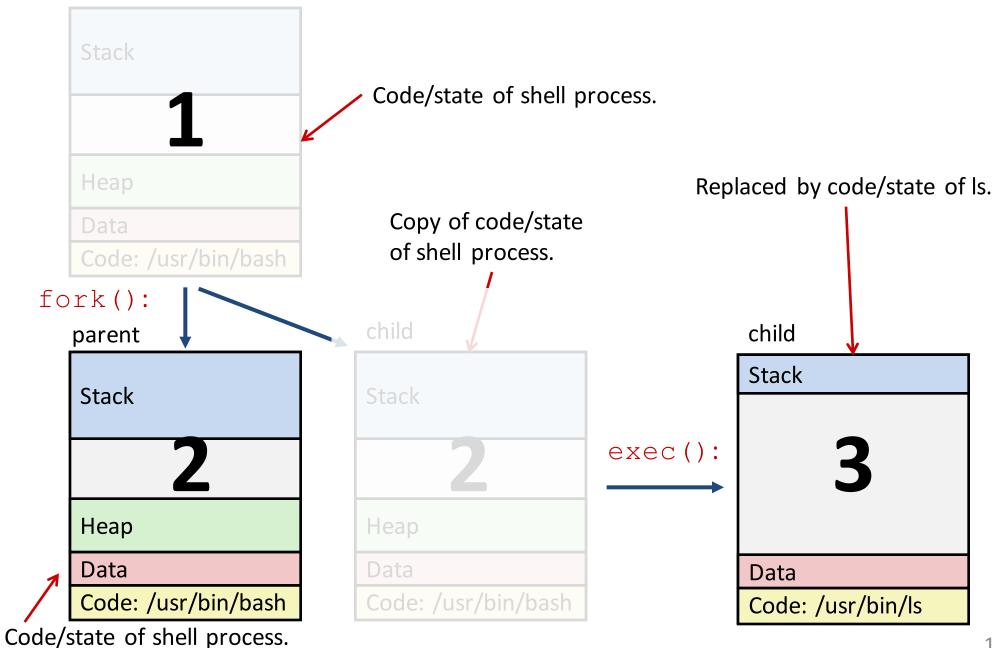
- **fork()** clone current process
- **execv()** replace process code and context (registers, memory) with a fresh program.

See man 3 execv, man 2 execve

```
// Example arguments: path="/usr/bin/ls",
// argv[0]="/usr/bin/ls", argv[1]="-ahl", argv[2]=NULL
void fork_exec(char* path, char* argv[]) {
    pid_t pid = fork();
    if (pid != 0) {
        printf("Parent: created a child %d\n", pid);
    } else {
        printf("Child: exec-ing new program now\n");
        execv(path, argv);
    }
    printf("This line printed by parent only!\n");
```

# **Exec-ing a new program**

When you run the command ls in a shell:



## execv: load/start program

### loads/starts program in current process:

Executable **filename** 

With argument list argv

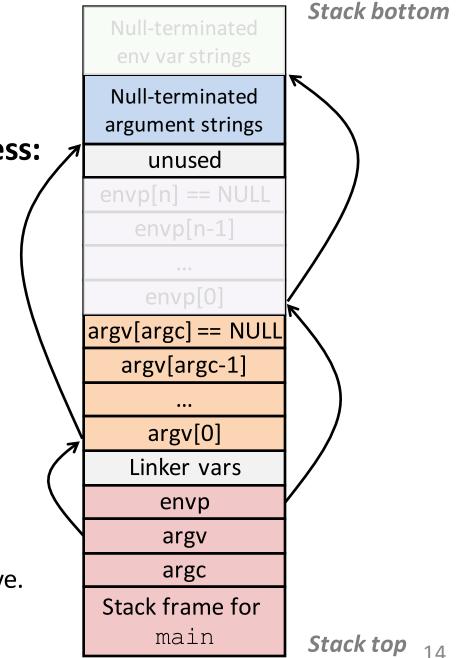
#### overwrites code, data, and stack

Keeps pid, open files, a few other items

#### does not return

unless error

Also sets up environment. See also: execve.



wait for child processes to terminate

pid\_t waitpid(pid\_t pid, int\* stat, int ops)

Suspend current process (i.e. parent) until child with **pid** ends.

On success:

Return **pid** when child terminates.

Reap child.

If stat != NULL, waitpid saves termination reason where it points.

See also: man 3 waitpid



#### **Terminated process still consumes system resources**

Reaping with wait/waitpid

#### What if parent doesn't reap?

If any parent terminates without reaping a child, then child will be reaped by init process (pid == 1)

What if parent runs a long time? *e.g.*, shells and servers

```
HCBve
waitpid example
void fork wait() {
  int child status;
  pid t child pid == fork();
  if (child pid == 0) {
    printf("HC: hello from child\n");
  } else {
    if (-1 == waitpid(child pid, &child status, 0) {
      perror("waitpid");
      exit(1);
    }
    printf("CT: child %d has terminated\n",
           child pid);
  }
  printf("Bye\n");
  exit(0);
}
```

## **Error-checking**

#### Check return results of system calls for errors! (No exceptions.)

Read documentation for return values.

Use perror to report error, then exit.

### void perror(char\* message)

Print "<message>: <reason that last system call failed.>"