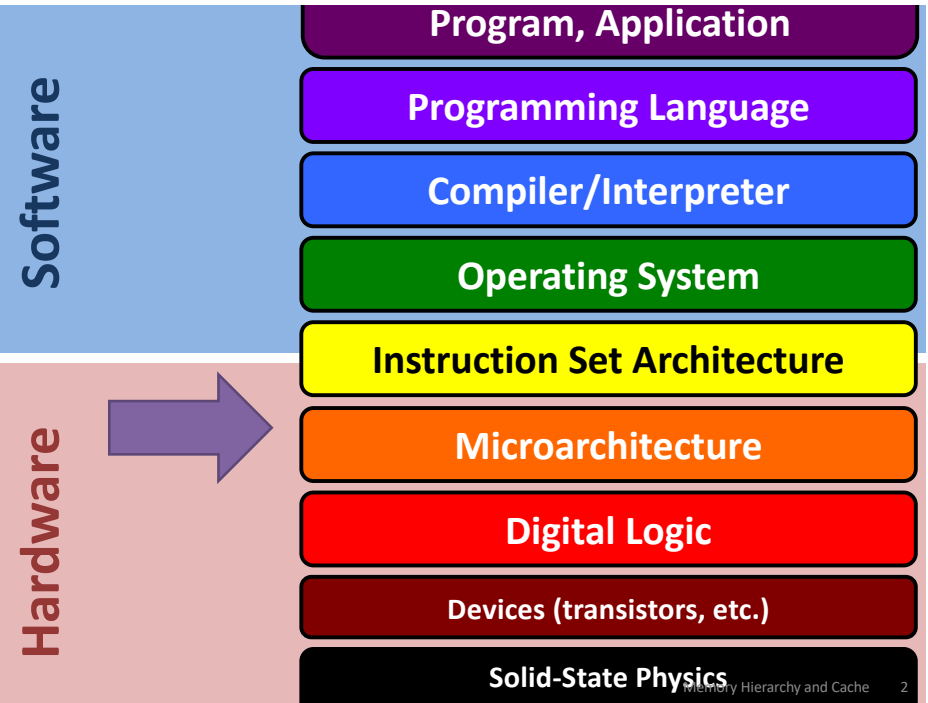




Memory Hierarchy and Cache

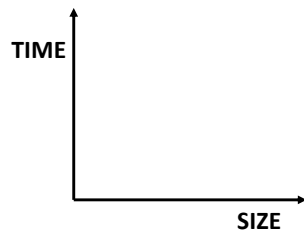
Memory hierarchy
Cache basics
Locality
Cache organization
Cache-aware programming



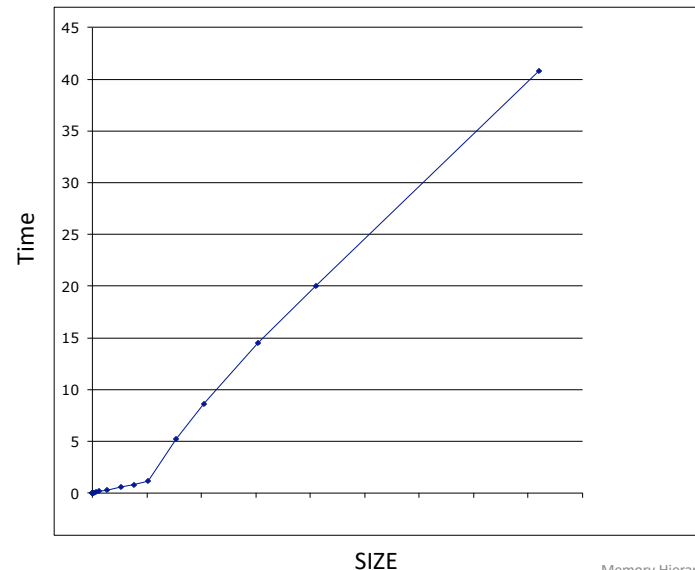
How does execution time grow with SIZE?

```
int array[SIZE];
fillArrayRandomly(array);
int s = 0;

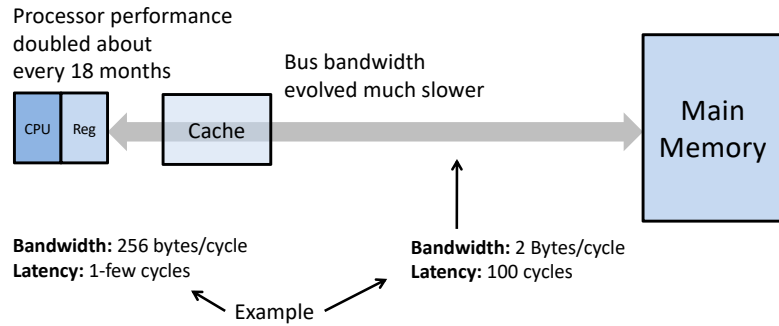
for (int i = 0; i < 200000; i++) {
    for (int j = 0; j < SIZE; j++) {
        s += array[j];
    }
}
```



Reality



Processor-memory bottleneck



Solution: caches

Cache

English:

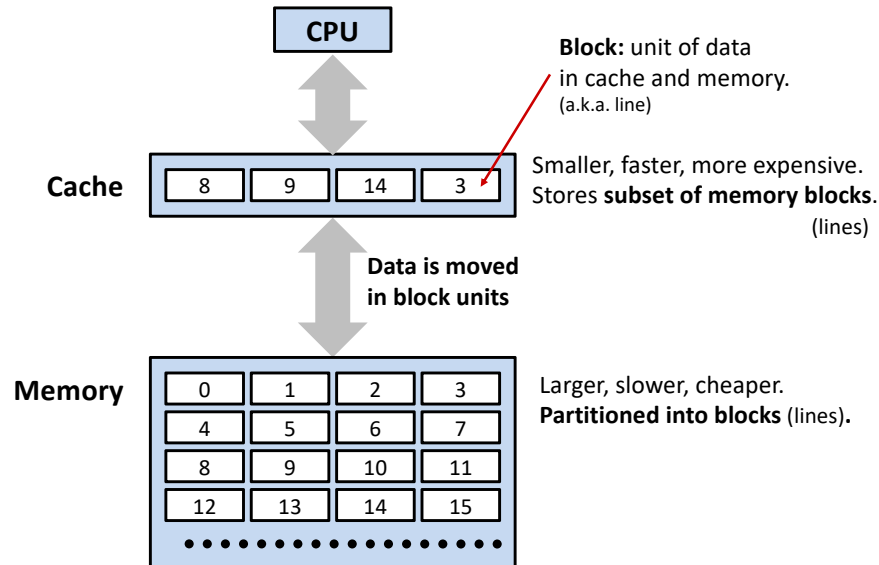
- n.* a hidden storage space for provisions, weapons, or treasures
- v.* to store away in hiding for future use

Computer Science:

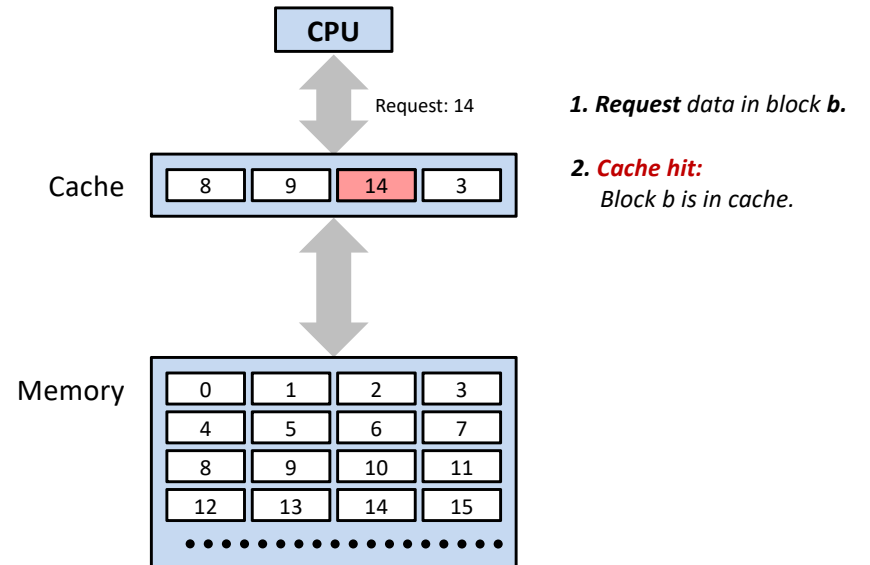
- n.* a computer memory with short access time used to store frequently or recently used instructions or data
- v.* to store [data/instructions] temporarily for later quick retrieval

Also used more broadly in CS: software caches, file caches, etc.

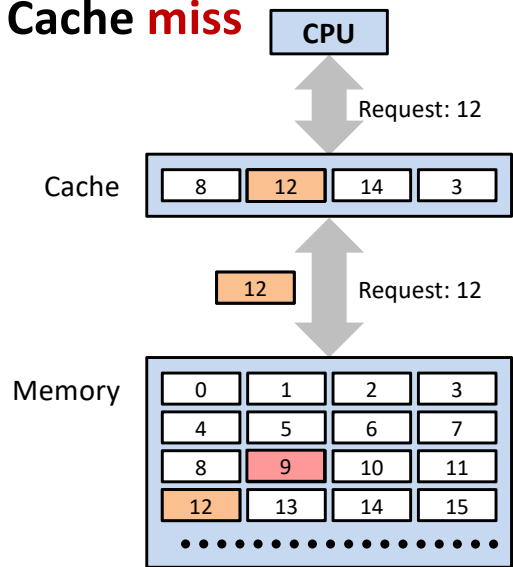
General cache mechanics



Cache hit



Cache miss



1. **Request data in block *b*.**
2. **Cache miss:**
block is *not* in cache
3. **Cache eviction:**
Evict a block to make room,
maybe store to memory.
4. **Cache fill:**
Fetch block from memory,
store in cache.

Placement Policy:
where to put block in cache

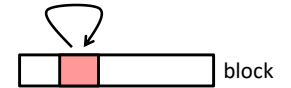
Replacement Policy:
which block to evict

Locality: why caches work

Programs tend to use data and instructions at addresses near or equal to those they have used recently.

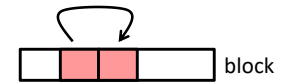
Temporal locality:

Recently referenced items are *likely* to be referenced again in the near future.



Spatial locality:

Items with nearby addresses are *likely* to be referenced close together in time.



How do caches exploit temporal and spatial locality?

Locality #1

```
sum = 0;
for (i = 0; i < n; i++) {
    sum += a[i];
}
return sum;
```

Data:

Instructions:

What is stored in memory?

Locality #2

```
int sum_array_rows(int a[M][N]) {
    int sum = 0;

    for (int i = 0; i < M; i++) {
        for (int j = 0; j < N; j++) {
            sum += a[i][j];
        }
    }
    return sum;
}
```

row-major M x N 2D array in C

a[0][0]	a[0][1]	a[0][2]	a[0][3]
a[1][0]	a[1][1]	a[1][2]	a[1][3]
a[2][0]	a[2][1]	a[2][2]	a[2][3]

Locality #3

row-major M x N 2D array in C

```
int sum_array_cols(int a[M][N]) {
    int sum = 0;

    for (int j = 0; j < N; j++) {
        for (int i = 0; i < M; i++) {
            sum += a[i][j];
        }
    }
    return sum;
}
```

a[0][0]	a[0][1]	a[0][2]	a[0][3]
a[1][0]	a[1][1]	a[1][2]	a[1][3] ...
a[2][0]	a[2][1]	a[2][2]	a[2][3]
		...	

Locality #4

```
int sum_array_3d(int a[M][N][N]) {
    int sum = 0;

    for (int i = 0; i < N; i++) {
        for (int j = 0; j < N; j++) {
            for (int k = 0; k < M; k++) {
                sum += a[k][i][j];
            }
        }
    }
    return sum;
}
```

What is "wrong" with this code?

How can it be fixed?

Cost of cache misses

Miss cost could be 100 × hit cost.

99% hits could be twice as good as 97%. How?

Assume cache hit time of 1 cycle, miss penalty of 100 cycles

Mean access time:

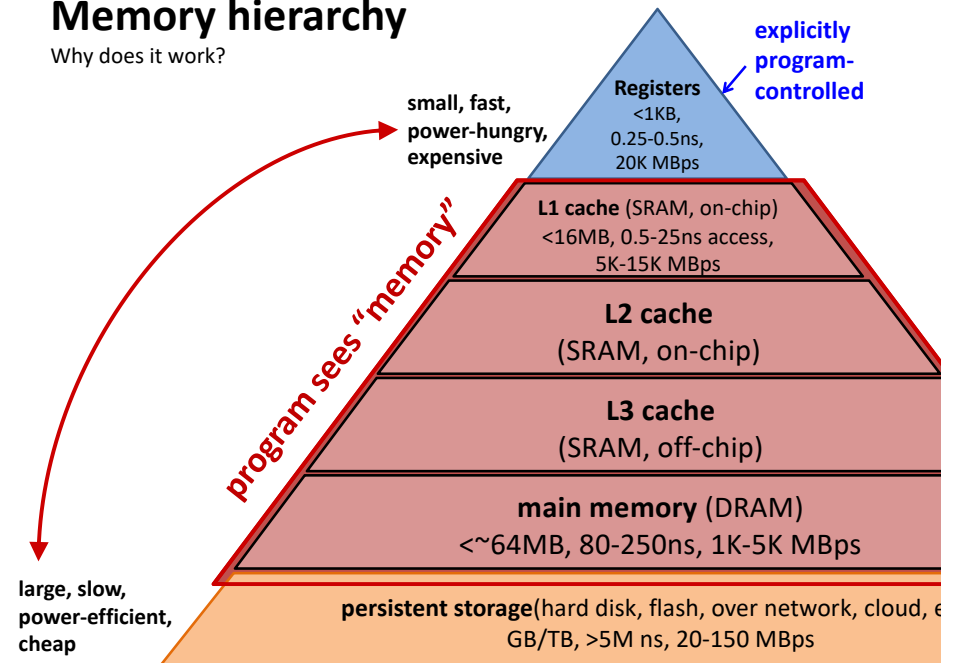
97% hits: $(0.97 * 1 \text{ cycle}) + (0.03 * 100 \text{ cycles}) = 3.97 \text{ cycles}$

99% hits: $(0.99 * 1 \text{ cycle}) + (0.01 * 100 \text{ cycles}) = 1.99 \text{ cycles}$

hit/miss rates

Memory hierarchy

Why does it work?



Cache performance metrics

Miss Rate

Fraction of memory accesses to data not in cache (misses / accesses)
 Typically: 3% - 10% for L1; maybe < 1% for L2, depending on size, etc.

Hit Time

Time to find and deliver a block in the cache to the processor.
 Typically: 1 - 2 clock cycles for L1; 5 - 20 clock cycles for L2

Miss Penalty

Additional time required on cache miss = main memory access time
 Typically 50 - 200 cycles for L2 (trend: increasing!)

Cache organization

Block

Fixed-size unit of data in memory/cache

Placement Policy

Where in the cache should a given block be stored?

- direct-mapped, set associative

Replacement Policy

What if there is no room in the cache for requested data?

- least recently used, most recently used

Write Policy

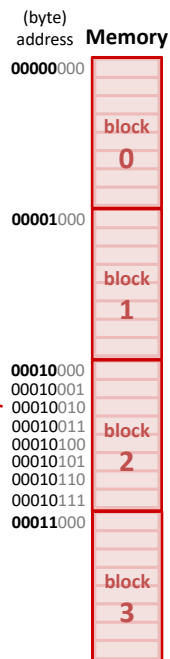
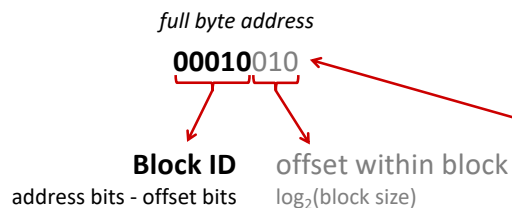
When should writes update lower levels of memory hierarchy?

- write back, write through, write allocate, no write allocate

Blocks

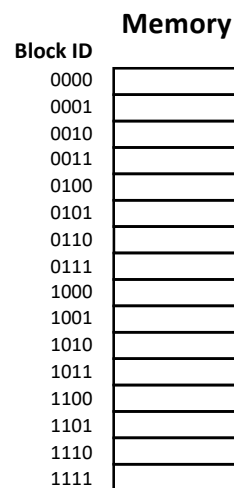
Divide address space into fixed-size aligned blocks.
 power of 2

Example: block size = 8

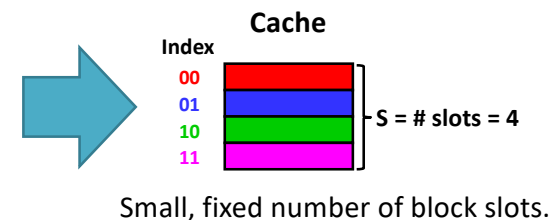


Note: drawing address order differently from here on!

Placement policy

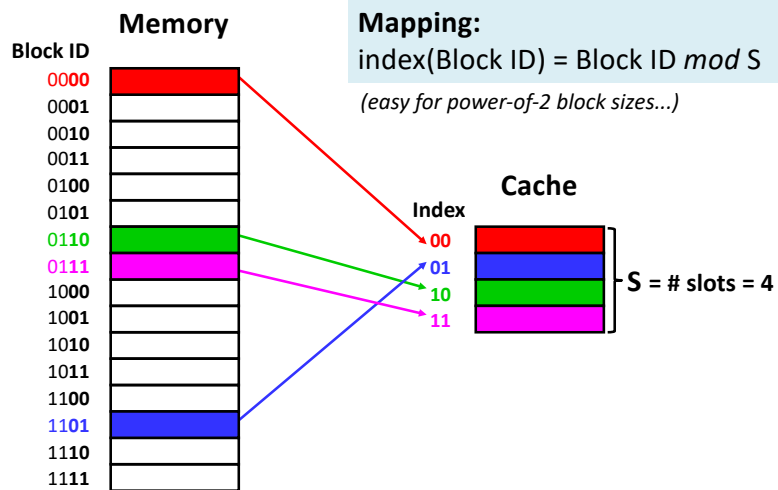


Mapping:
 index(Block ID) = ???

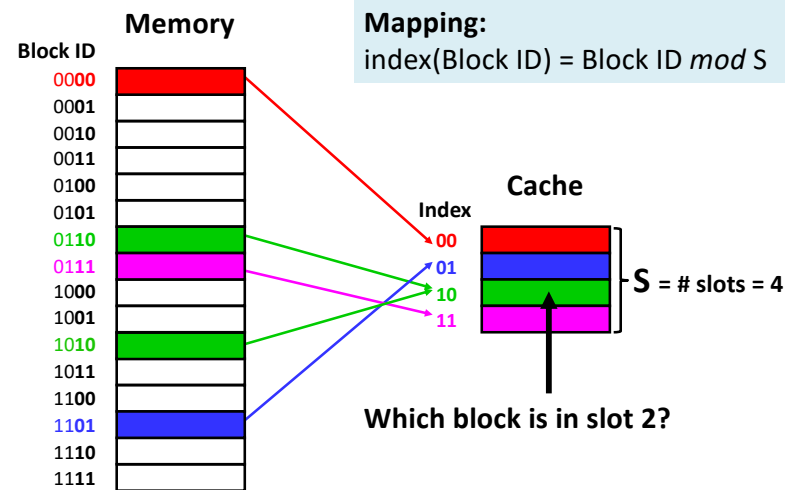


Large, fixed number of block slots.

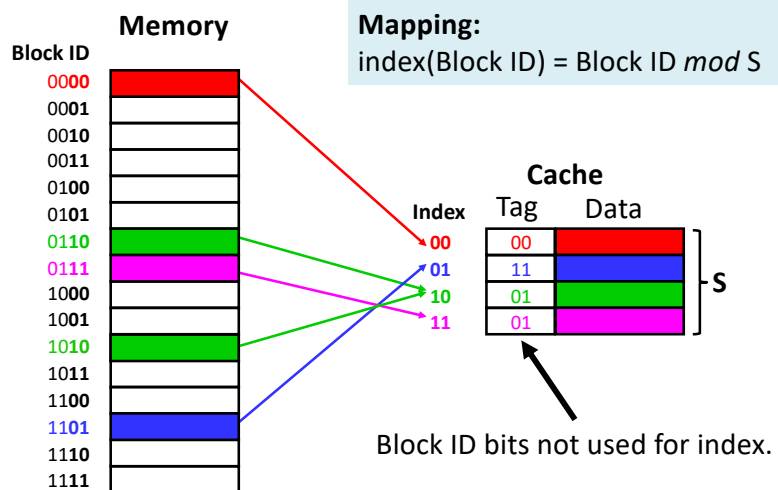
Placement: *direct-mapped*



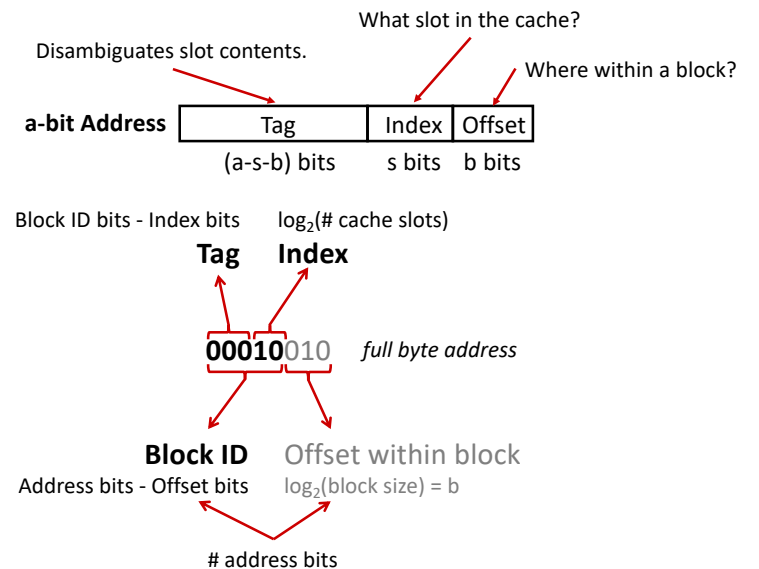
Placement: mapping ambiguity?



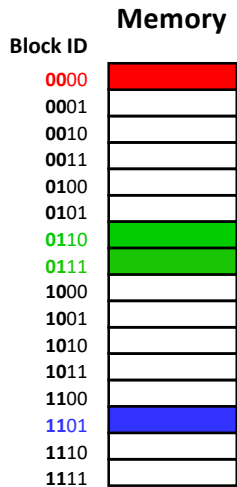
Placement: tags resolve ambiguity



Address = tag, index, offset

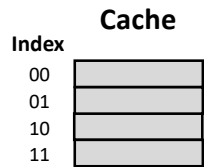


Placement: ~~direct-mapped~~



Why not this mapping?
 $\text{index}(\text{Block ID}) = \text{Block ID} / S$

(still easy for power-of-2 block sizes...)

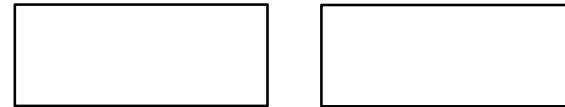


Puzzle #1

Cache starts *empty*.

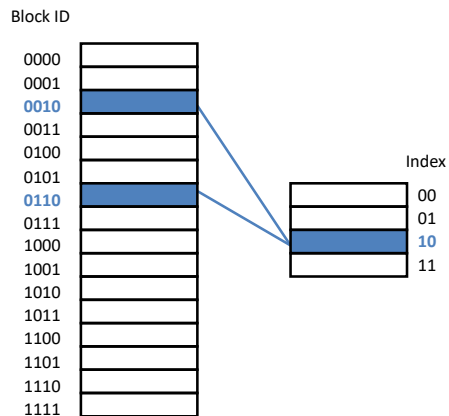
Access (address, hit/miss) stream:

(10, miss), (11, hit), (12, miss)



What could the block size be?

Placement: direct-mapping conflicts



What happens when accessing in repeated pattern:

0010, 0110, 0010, 0110, 0010...?

cache conflict

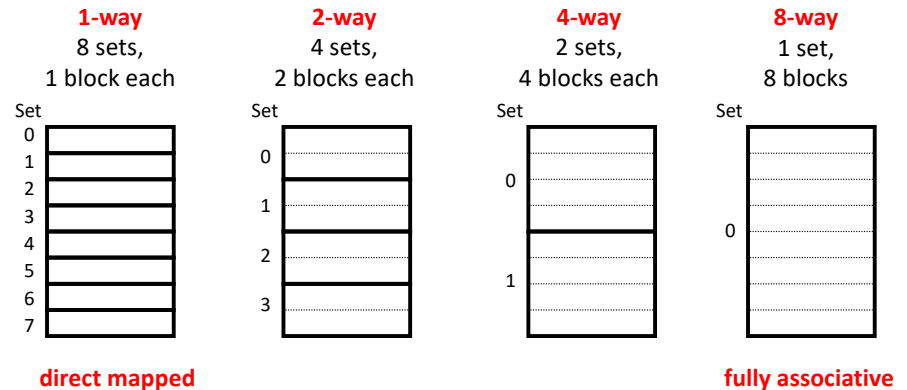
Every access suffers a miss, evicts cache line needed by next access.

Placement: ~~set-associative~~

$S = \# \text{ slots in cache}$

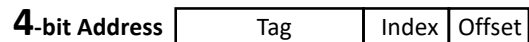
One index per *set* of block slots.
 Store block in **any** slot within set.

Mapping:
 $\text{index}(\text{Block ID}) = \text{Block ID} \bmod S$



Replacement policy: if set is full, what block should be replaced?
 Common: **least recently used (LRU)**
 but hardware may implement "not most recently used"

Example: tag, index, offset? #1



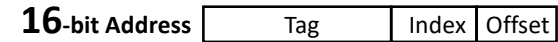
Direct-mapped
4 slots
2-byte blocks

tag bits _____
set index bits _____
block offset bits _____

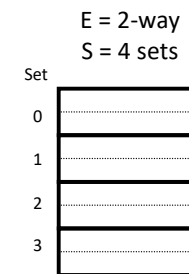
index(1101) = _____

Example: tag, index, offset? #2

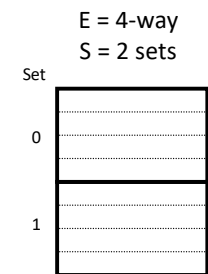
E-way set-associative
S slots
16-byte blocks



tag bits _____
set index bits _____
block offset bits _____
index(0x1833) _____



tag bits _____
set index bits _____
block offset bits _____
index(0x1833) _____



tag bits _____
set index bits _____
block offset bits _____
index(0x1833) _____

Replacement policy

If set is full, what block should be replaced?

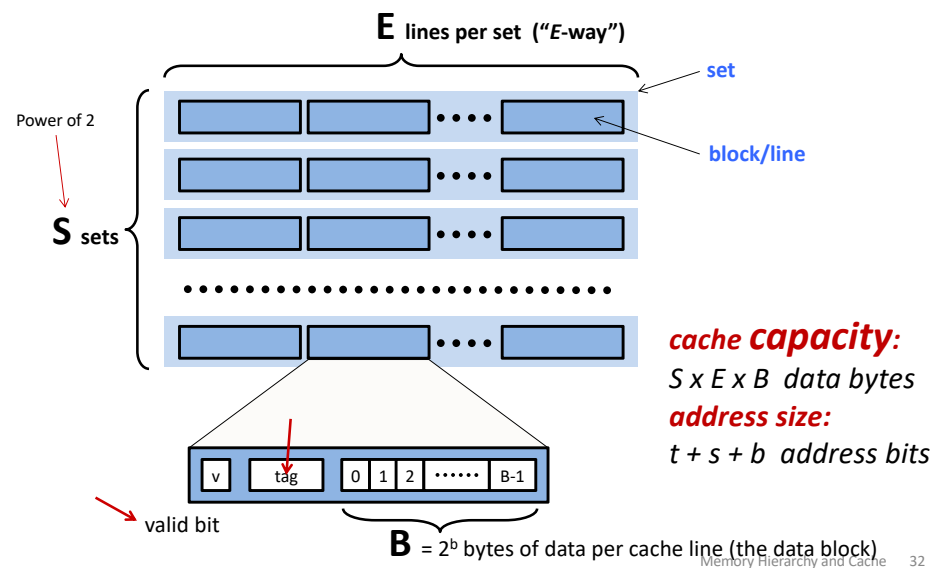
Common: **least recently used (LRU)**
(but hardware usually implements "not most recently used")

Another puzzle: Cache starts *empty*, uses LRU.

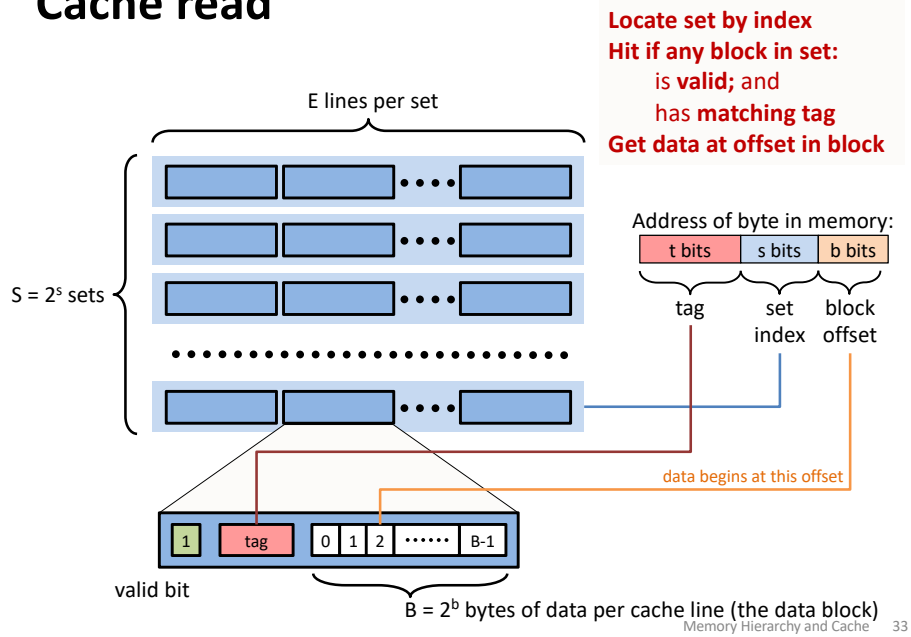
Access (address, hit/miss) stream:
(10, miss); (12, miss); (10, miss)

associativity of cache?

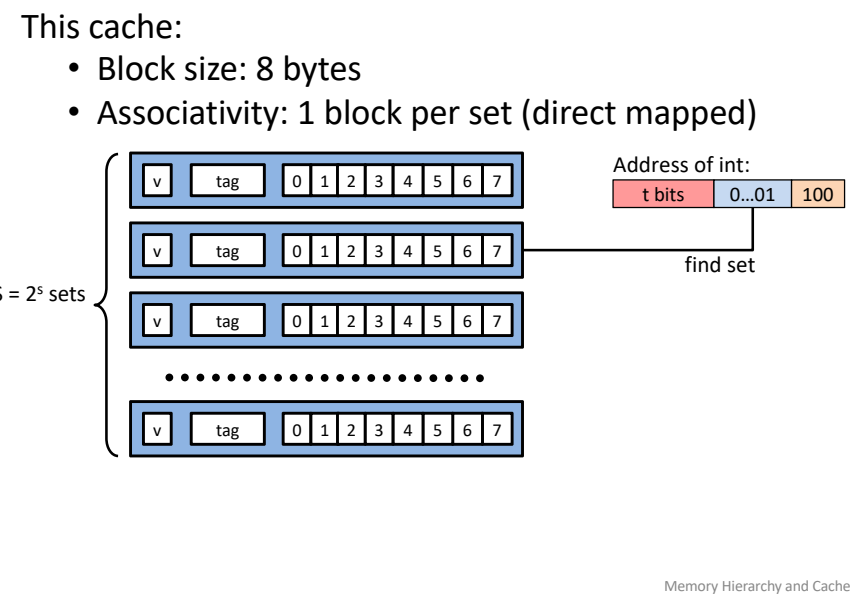
General cache organization (S, E, B)



Cache read

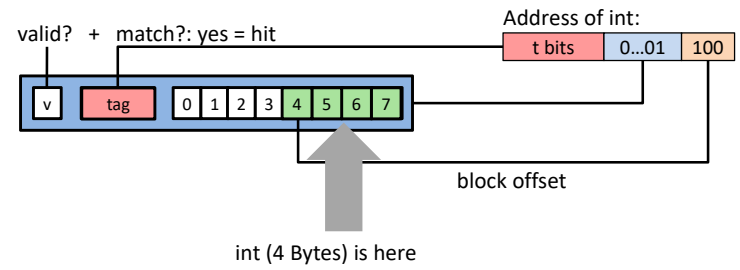


Cache read: direct-mapped (E = 1)



Cache read: direct-mapped (E = 1)

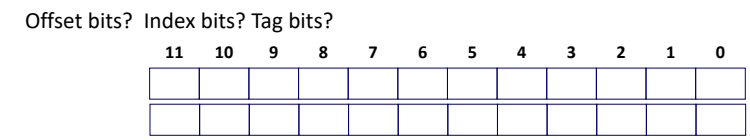
- This cache:
- Block size: 8 bytes
 - Associativity: 1 block per set (direct mapped)



If no match: old line is evicted and replaced

Direct-mapped cache practice

12-bit address Access 0x354
16 lines, 4-byte block size
Direct mapped Access 0xA20



Index	Tag	Valid	B0	B1	B2	B3
0	19	1	99	11	23	11
1	15	0	-	-	-	-
2	1B	1	00	02	04	08
3	36	0	-	-	-	-
4	32	1	43	6D	8F	09
5	0D	1	36	72	F0	1D
6	31	0	-	-	-	-
7	16	1	11	C2	DF	03

Index	Tag	Valid	B0	B1	B2	B3
8	24	1	3A	00	51	89
9	2D	0	-	-	-	-
A	2D	1	93	15	DA	3B
B	0B	0	-	-	-	-
C	12	0	-	-	-	-
D	16	1	04	96	34	15
E	13	1	83	77	1B	D3
F	14	0	-	-	-	-

Example #1 (E = 1)

Locals in registers.

Assume **a** is aligned such that

&a[r][c] is **aa...a rrrr cccc 000**

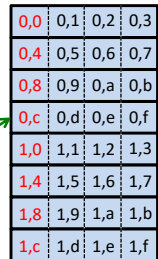
```
int sum_array_rows(double a[16][16]){
    double sum = 0;

    for (int r = 0; r < 16; r++){
        for (int c = 0; c < 16; c++){
            sum += a[r][c];
        }
    }
    return sum;
}
```

```
int sum_array_cols(double a[16][16]){
    double sum = 0;

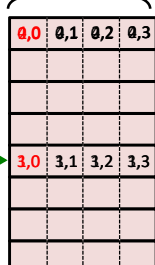
    for (int c = 0; c < 16; c++){
        for (int r = 0; r < 16; r++){
            sum += a[r][c];
        }
    }
    return sum;
}
```

Assume: cold (empty) cache
3-bit set index, 5-bit offset
 aa...arr rc cc000
0,0: aa...a000 000 00000



32 bytes = 4 doubles
 every access a miss
 16*16 = 256 misses

32 bytes = 4 doubles
 4 misses per row of array
 4*16 = 64 misses



Example #2 (E = 1)

block = 16 bytes; 8 sets in cache
 How many block offset bits?
 How many set index bits?

```
int dotprod(int x[8], int y[8]) {
    int sum = 0;

    for (int i = 0; i < 8; i++) {
        sum += x[i]*y[i];
    }
    return sum;
}
```

Address bits:

B =

S =

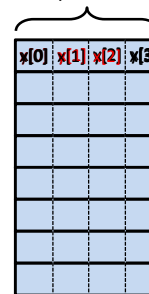
Addresses as bits

0x00000000:

0x00000080:

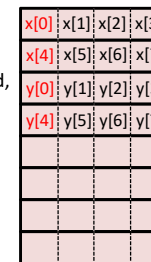
0x000000A0:

16 bytes = 4 ints



if x and y are mutually aligned,
 e.g., 0x00, 0x80

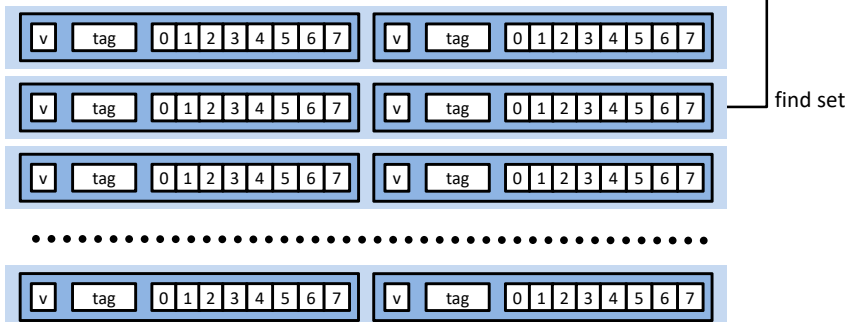
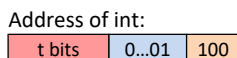
if x and y are mutually unaligned,
 e.g., 0x00, 0xA0



Cache read: set-associative (Example: E = 2)

This cache:

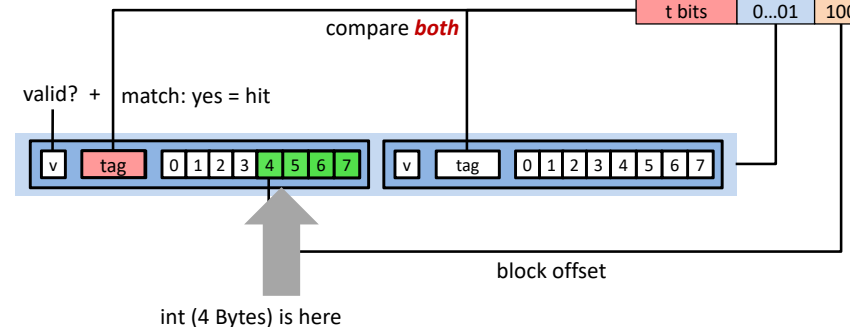
- Block size: 8 bytes
- Associativity: 2 blocks per set



Cache read: set-associative (Example: E = 2)

This cache:

- Block size: 8 bytes
- Associativity: 2 blocks per set



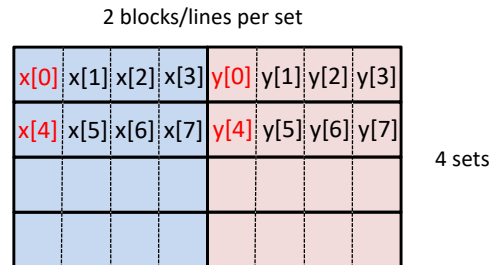
If no match: Evict and replace one line in set.

Example #3 (E = 2)

```
float dotprod(float x[8], float y[8]) {
    float sum = 0;

    for (int i = 0; i < 8; i++) {
        sum += x[i]*y[i];
    }
    return sum;
}
```

If x and y aligned,
e.g. &x[0] = 0, &y[0] = 128,
can still fit both because each set
has space for two blocks/lines



Types of Cache Misses

Cold (compulsory) miss

Conflict miss

Capacity miss

Which ones can we mitigate/eliminate? How?

Writing to cache

Multiple copies of data exist, must be kept in sync.

Write-hit policy

Write-through:

Write-back: needs a *dirty bit*

Write-miss policy

Write-allocate:

No-write-allocate:

Typical caches:

Write-back + Write-allocate, usually

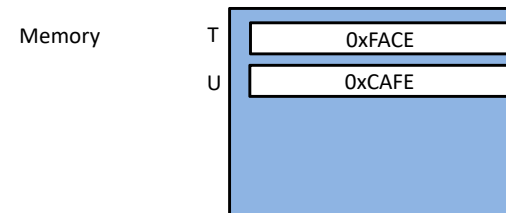
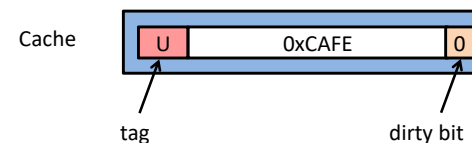
Write-through + No-write-allocate, occasionally

Write-back, write-allocate example

Cache/memory not involved

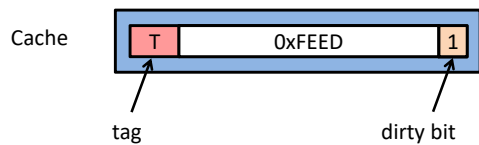
```
eax =
ecx = T
edx = U
```

1. `mov $T, %ecx`
2. `mov $U, %edx`
3. `mov $0xFEED, (%ecx)`
 - a. Miss on T.

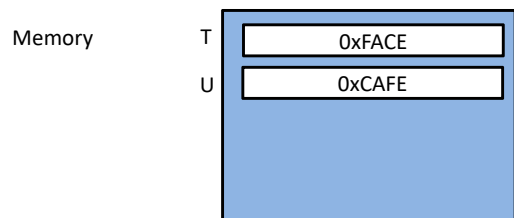


Write-back, write-allocate example

eax =
ecx = T
edx = U

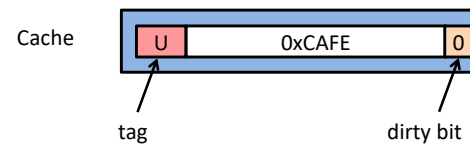


1. `mov $T, %ecx`
2. `mov $U, %edx`
3. `mov $0xFEED, (%ecx)`
 - a. Miss on T.
 - b. Evict U (clean: discard).
 - c. Fill T (write-allocate).
 - d. Write T in cache (dirty).
4. `mov (%edx), %eax`
 - a. Miss on U.

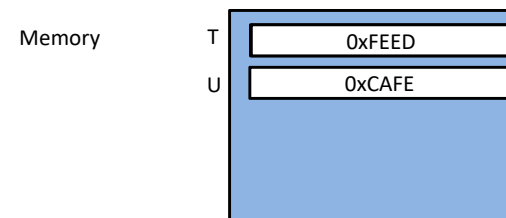


Write-back, write-allocate example

eax = 0xCAFE
ecx = T
edx = U



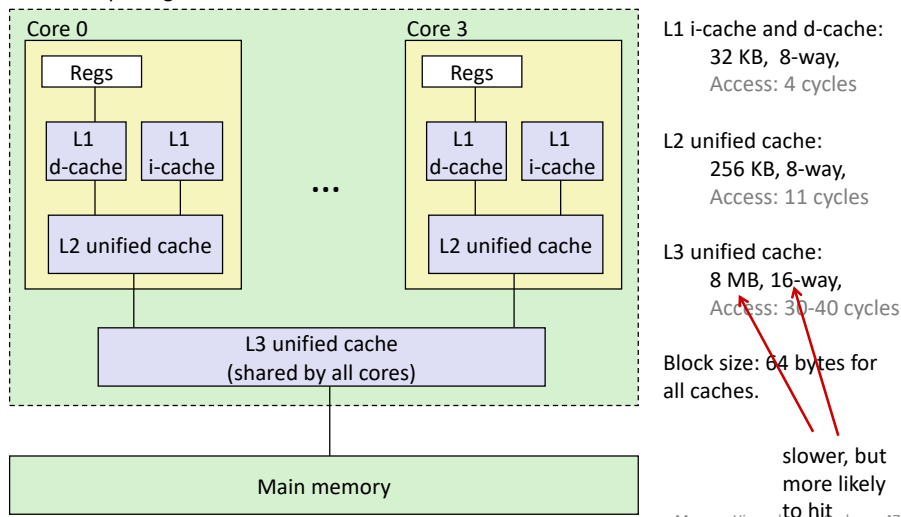
1. `mov $T, %ecx`
2. `mov $U, %edx`
3. `mov $0xFEED, (%ecx)`
 - a. Miss on T.
 - b. Evict U (clean: discard).
 - c. Fill T (write-allocate).
 - d. Write T in cache (dirty).
4. `mov (%edx), %eax`
 - a. Miss on U.
 - b. Evict T (dirty: write back).
 - c. Fill U.
 - d. Set %eax.
5. **DONE.**



Example memory hierarchy

Typical laptop/desktop processor
(c.a. 201_)

Processor package



(Aside) Software caches

Examples

File system buffer caches, web browser caches, database caches, network CDN caches, etc.

Some design differences

Almost always fully-associative

Often use complex replacement policies

Not necessarily constrained to single "block" transfers

Cache-friendly code

Locality, locality, locality.

Programmer can optimize for cache performance

- Data structure layout

- Data access patterns

 - Nested loops

 - Blocking (see CSAPP 6.5)

All systems favor “cache-friendly code”

- Performance is hardware-specific

- Generic rules capture most advantages

 - Keep working set small (temporal locality)

 - Use small strides (spatial locality)

 - Focus on inner loop code