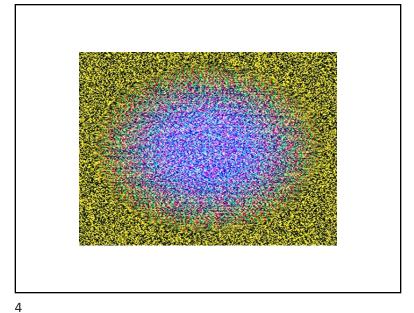
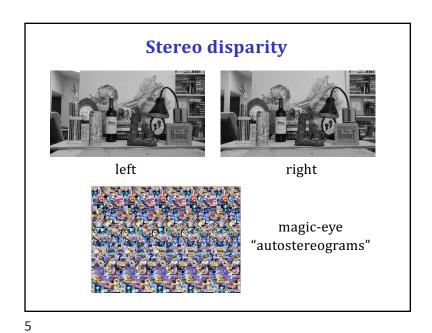


## 

First stereoscope invented by Sir Charles Wheatstone, 1838





Stereo viewing geometry

LEFT

RIGHT

positive stereo disparity

in front of fixation point

negative stereo disparity

in back of fixation point

zero disparity

Stereo viewing geometry

LEFT

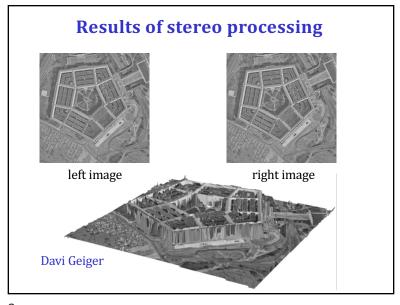
RIGHT

larger stereo disparity

further away in depth from fixation point

RIGHT

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## **Steps of the stereo process**





left

right

- extract features from the left and right images, whose stereo disparity will be measured
- match the left and right image features and measure their disparity in position

"stereo correspondence problem"

• use stereo disparity to compute depth

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## **Constraints on stereo correspondence**

• Uniqueness

each feature in the left image matches with only one feature in the right (and vice versa...)

Similarity

matching features appear "similar" in the two images

• Continuity

nearby image features have similar disparities

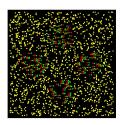
• Epipolar constraint

simple version: matching features have similar vertical positions, but... (stay tuned...)

## Random-dot stereograms







- Bela Julesz, 1971
- stereo system can function independently
- we can match "simple" features
- highlight the *ambiguity* of the matching process

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